

# ZHENYU YE

Address: Jan van Mierlolaan 1, 1183WH Amstelveen, The Netherlands

Email: zhenyu.z.ye@gmail.com ◊ Tel: +31(0)622157906 ◊ Homepage: <http://zhenyu-ye.net/>

## SUMMARY

---

Multiple years of hands-on experience in the design and implementation of compute-intensive algorithms, electronic systems, and mechatronic systems. Experience in commercial product development in an agile environment. Experience in collaboration across multiple functional domains, cultures, and in both academic and industrial environments.

## PROFESSIONAL EXPERIENCE

---

**Hardware and Devices Engineer, Connecterra** *2016 July - current*  
Hardware, firmware, and software for low-power and wireless Internet-of-things devices.

.....

**Firmware Engineer, Intel** *2014 August - 2016 June*  
Implementation of firmware for next generation image signal processors. Major activities:

- Implementation of firmware stack for customized circuits and signal processors.
  - Support Windows and Android driver teams for bringing up and troubleshooting device features.
  - Interact with image algorithm designers for implementation and interface of firmware.
  - Practice software design process and agile development method.
- .....

**Guest lecturing on visual computing on GPUs, TU Eindhoven** *2009 - 2016*  
◊ Giving lectures on GPU architectures and programming for a master level course.  
◊ Between 2009 - 2013, also assisting hands-on labs on the implementation and optimization of various image and vision algorithms on GPUs: histogram equalization (2009), stereo vision (2010), natural feature detection (2011), face detection (2012), and neural networks for object recognition (2013).

.....

**Researcher, Embedded vision, TU Delft** *2014 April - July*  
Implementation and optimization of a proprietary computer vision algorithm on parallel processing platforms. The project later turns into a startup, QdepQ.

.....

**PhD researcher, Embedded vision architecture, TU Eindhoven** *2009 - 2014*  
◊ Design of vision algorithms and electronic systems for 1000 frames-per-second vision processing.  
◊ Implementation of vision based closed-loop control systems, a.k.a. "vision-in-the-loop" systems, for precision motion control (see my homepage for a demo).  
◊ Cooperation with multiple industrial partners (e.g., Roth & Rau B.V.) and a multidisciplinary team consisting of electronic engineers, computer vision scientists, and control engineers.

Major achievements:

- High-speed vision processing on field-programmable gate arrays (FPGAs).
- Implementation of micro-/nano-scale visual servo control systems.
- Multi-domain modeling of data-intensive and compute-intensive mechatronic systems.

Relevant knowledge and skills:

- **Electronic systems:** parallel architecture, register-transfer level (RTL) design using hardware description languages (e.g., VHDL/Verilog), high-level-synthesis tools (various vendors), FPGA tool-chains (various vendors), high-speed interfaces for image sensors and cameras (e.g., LVDS, CameraLink).
- **Embedded software:** C/C++ targeting various embedded processors (e.g., DSP, Microblaze), single-instruction-multiple-data (SIMD) extensions (e.g., Intel SSE), programming graphics processing units (GPUs) with CUDA and OpenCL, multi-threading on multi-core processors (e.g., pthread, OpenMP), real-time operating systems (e.g., Real-Time Linux), scripts (e.g., Python).
- **Image processing:** design of hardware-friendly image processing algorithms from scratch and from existing libraries (e.g., Matlab, OpenCV), image processing on CPU/DSP/GPUs/FPGAs, full-system implementation of high-speed (1000 fps) imaging platform.
- **Mechatronics systems:** digital and analog interface (e.g., various ADC/DAC), motor encoder and actuator interface, design of feedforward and feedback controllers, modeling and simulation (e.g., in Matlab/Simulink), performance tuning for measurement noise and delay of visual feedback.
- **Modeling, simulation, analysis:** analytical performance model of image processing systems, quality analysis of vision algorithms for control purposes, multi-domain modeling and integration, customized full-system simulation framework, system-wide bottleneck analysis and optimization.

---

**Team member, Low-power image processor architecture, TU Eindhoven** *2009 - 2013*

Relevant knowledge and skills:

- **Processor architecture:** micro-architecture of processors (RISC/VLIW/SIMD), memory hierarchy optimization (e.g., configuration of register file and memory).
- **Embedded software:** assembly code level optimization on SIMD architecture.
- **Image processing:** design and implementation of hardware-friendly image processing algorithms.

---

**MSc project, GPU architecture and programming, TU Eindhoven** *2008 - 2009*

Relevant knowledge and skills:

- **GPU programming:** general purpose computing in CUDA, graphics pipeline in OpenGL.
- **Parallel computing:** parallel implementation of linear algebra algorithms (BLAS/LAPACK).
- **Modeling & simulation:** analytical models, simulators (e.g., SimpleScalar, GPGPU-Sim).

## EDUCATION

---

**PhD candidate, TU Eindhoven, The Netherlands** *2009 - 2017 (expected)*

Funded by the Embedded Vision Architecture project, in cooperation with the Dynamics & Control group and the Electronic Systems group of TU Eindhoven, and the Biorobotics Lab of TU Delft.

**MSc. (Ir.) in Embedded Systems, TU Eindhoven, The Netherlands** *2006 - 2009*

Funded by TU/e scholarship, with MSc. thesis on GPU architecture and programming.

**BSc., Electronic Engineering, Harbin Institute of Technology, China** *2002 - 2006*

BSc. project on the implementation and optimization of digital filters on DSPs.

## ADDITIONAL INFORMATION

---

**Personal info:** Nationality: P.R.China, Date of Birth: 16 Oct. 1983, Gender: Male

**Language skills:** English, Chinese, Dutch (A2-level, sufficient for koetjes-en-kalfjes)